



Some ξ -Pre-Continuous Maps

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Abstract. In this paper the concept of ξ -pre-continuous and ξ -regular continuous maps in ξ -topological spaces are introduced and all the possible relationships of these maps have been discussed and established. Further we introduce and study ξ -pre-generalized closed sets and ξ -pre-generalized continuity in ξ -topological spaces and investigate various relationship by making the use of some counter examples

Keywords: ξ -regular-continuous maps, totally ξ -pre-continuous maps, strongly ξ -pre continuous maps, totally ξ -regular-continuous maps, strongly ξ -regular-continuous maps, ξ -pre-generalized closed, ξ -generalized-pre closed, ξ -pre-generalized continuous maps, ξ -irresolute, ξ -pre-generalized irresolute.

1 Introduction

In both the pure and applied domains, the importance of general topology is quickly increasing. Information systems are fundamental instruments for generating information understanding in any real-life sector, and topological information collection structures are appropriate mathematical models for both quantitative and qualitative information mathematics. Initially, Mashhour et. al. [21] introduced pre-open sets and pre-continuity in topology. Levine [18] introduced the class of generalized closed (g-closed) sets in topological spaces. The generalized continuity was studied in recent years by Balachandran et.al. Devi et.al and Maki et.al [5,10,20]. Regular open sets have been introduced and investigated by Stone [27]. Miguel Caldas and Cueva introduced and studied the concept of semi-generalized continuous maps in topological spaces [7]. The authors Arya,S. P., Gupta,R Anuradha, Baby Chacko and Singh D [2-3,28] introduced the concept of strongly continuous functions and almost perfectly continuous functions in topological spaces and established the various significant results. Benchalli S.S and Umadevi I Neeli Nour T.M [4, 26] studied the concept of totally semi-continuous functions and semi-totally continuous functions in topological spaces and verify the certain properties of the concept. Bhattacharya,S, [6] introduced and studied the concept of generalized regular closed sets and establish the various characterizations. Nithyanantha and Thangavelu [23] introduced the concept of binary topology between two sets and investigate some of the basic properties, where a binary topology from X to Y is a binary structure satisfying certain axioms that are analogous to the axioms of topology. Jamal M. Mustafa [12] studied binary generalized topological spaces and investigate the various relationships of the maps so discussed with some other maps.

1.1 Contribution:

As outline, the concept ξ -pre-continuous and ξ -regular continuous map, ξ -pre-generalized closed sets, ξ -pre-generalized continuous maps and ξ -pre-irresolutes are introduced in ξ -topological spaces and investigate various relationships by making the use of some examples

1.2 Organization

The rest of the paper structured as follows: Some require basic definitions, concepts of ξ -topological and notations are discussed in Section 2. In section 3, namely **ξ -Pre-Continuous Maps** we have introduced several maps and have discussed their relationships also. In section 4, headed by the concept of **ξ -Regular Continuous Maps** we introduced several maps and studied their relationships. In section 5, headed by the concept of **ξ -Pre-Generalized Closed Sets and Maps** we introduced several closed sets and their maps and verify their relationships. Finally, Section 6 concludes the paper with possible scope of the concept. Throughout the paper $\wp(Y)$ denotes the power set of Y.

2. Preliminaries

Some require and important definitions and concepts of ξ -topological space and notations have been given in this portion

Definition 2.1: Let Y_1 and Y_2 be any two non-void sets. Then ξ -topology (ξ_T) from Y_1 to Y_2 is a binary structure $\xi \subseteq \wp(Y_1) \times \wp(Y_2)$ satisfying the conditions i.e. $(\emptyset, \emptyset), (Y_1, Y_2) \in \xi$ and If $\{(L_\alpha, M_\alpha); \alpha \in \Gamma\}$ is a family of elements of ξ , then $(\cup_{\alpha \in \Gamma} L_\alpha, \cup_{\alpha \in \Gamma} M_\alpha) \in \xi$. If ξ is ξ_T from Y_1 to Y_2 , then (Y_1, Y_2, ξ) is called a ξ -topological space (ξ_T S) and the elements of ξ are called the ξ -open subsets of (Y_1, Y_2, ξ) . The elements of $Y_1 \times Y_2$ are called simply ξ -points.

Definition 2.2: Let Y_1 and Y_2 be any two non-void set and $(L_1, M_1), (L_2, M_2)$ are the elements of $\wp(Y_1) \times \wp(Y_2)$. Then $(L_1, M_1) \subseteq (L_2, M_2)$ only if $L_1 \subseteq L_2$ and $M_1 \subseteq M_2$.

Remark 2.1: Let $\{T_\alpha; \alpha \in \Lambda\}$ be the family of ξ_T from Y_1 to Y_2 . Then, $\cap_{\alpha \in \Lambda} T_\alpha$ is also ξ_T from Y_1 to Y_2 . Further $\cup_{\alpha \in \Lambda} T_\alpha$ need not be ξ_T .

Definition 2.3: Let (Y_1, Y_2, ξ) be a ξ_T S and $L \subseteq Y_1, M \subseteq Y_2$. Then (L, M) is called ξ -closed in (Y_1, Y_2, ξ) if $(Y_1 \setminus L, Y_2 \setminus M) \in \xi$.

Proposition 2.1: Let (Y_1, Y_2, ξ) is ξ_T S. Then (Y_1, Y_2) and (\emptyset, \emptyset) are ξ -closed sets. Similarly if $\{(L_\alpha, M_\alpha); \alpha \in \Gamma\}$ is a family of ξ -closed sets, then $(\cap_{\alpha \in \Gamma} L_\alpha, \cap_{\alpha \in \Gamma} M_\alpha)$ is ξ -closed.

Definition 2.4: Let (Y_1, Y_2, ξ) is ξ_T S and $(L, M) \subseteq (Y_1, Y_2)$. Let $(L, M)^{1^*}_\xi = \cap \{L_\alpha: (L_\alpha, M_\alpha) \text{ is } \xi\text{-closed set and } (L, M) \subseteq (L_\alpha, M_\alpha)\}$ and $(L, M)^{2^*}_\xi = \cap \{M_\alpha: (L_\alpha, M_\alpha) \text{ is } \xi\text{-closed set and } (L, M) \subseteq (L_\alpha, M_\alpha)\}$. Then $(L, M)^{1^*}_\xi, (L, M)^{2^*}_\xi$ is ξ -closed set and $(L, M) \subseteq (L, M)^{1^*}_\xi, (L, M)^{2^*}_\xi$. The ordered pair $((L, M)^{1^*}_\xi, (L, M)^{2^*}_\xi)$ is called ξ -closure of (L, M) and is denoted $Cl_\xi(L, M)$ in ξ_T S (X, Y, μ) where $(L, M) \subseteq (Y_1, Y_2)$.

Proposition 2.2: Let $(L, M) \subseteq (Y_1, Y_2)$. Then (L, M) is ξ -open in (Y_1, Y_2, ξ) iff $(L, M) = I_\xi(L, M)$ and (L, M) is ξ -closed in (Y_1, Y_2, ξ) iff $(L, M) = Cl_\xi(L, M)$.

Proposition 2.3: Let $(L, M) \subseteq (N, P) \subseteq (Y_1, Y_2)$ and (Y_1, Y_2, ξ) is ξ_T S. Then $Cl_\xi(\emptyset, \emptyset) = (\emptyset, \emptyset)$, $Cl_\xi(X, Y) = (X, Y)$, $(L, M) \subseteq Cl_\xi(L, M)$, $(L, M)^{1^*}_\xi \subseteq (N, P)^{1^*}_\xi$, $(L, M)^{2^*}_\xi \subseteq (N, P)^{2^*}_\xi$, $Cl_\xi(L, M) \subseteq Cl_\xi(N, P)$ and $Cl_\xi(Cl_\xi(L, M)) = Cl_\xi(L, M)$

Definition 2.5: Let (Y_1, Y_2, ξ) is ξ_T S and $(L, M) \subseteq (Y_1, Y_2)$. Let $(L, M)^{1^0}_\xi = \cup \{L_\alpha: (L_\alpha, M_\alpha) \text{ is } \xi\text{-open set and } (L, M) \subseteq (L_\alpha, M_\alpha)\}$ and $(L, M)^{2^0}_\xi = \cup \{M_\alpha: (L_\alpha, M_\alpha) \text{ is } \xi\text{-open set and } (L, M) \subseteq (L_\alpha, M_\alpha)\}$. Then $(L, M)^{1^0}_\xi, (L, M)^{2^0}_\xi$ is ξ -open set and $(L, M)^{1^0}_\xi, (L, M)^{2^0}_\xi \subseteq (L, M)$. The ordered pair $((L, M)^{1^0}_\xi, (L, M)^{2^0}_\xi)$ is called ξ -interior of (L, M) and is denoted $I_\xi(L, M)$ in ξ_T S (X, Y, μ) where $(L, M) \subseteq (Y_1, Y_2)$.

Proposition 2.4: Let $(L, M) \subseteq (Y_1, Y_2)$. Then (L, M) is ξ -open set in (Y_1, Y_2, ξ) iff $(L, M) = I_\xi(L, M)$.

Proposition 2.5: Let $(L, M) \subseteq (N, P) \subseteq (Y_1, Y_2)$ and (Y_1, Y_2, ξ) is ξ_T S. Then $I_\xi(\emptyset, \emptyset) = (\emptyset, \emptyset)$, $I_\xi(X, Y) = (X, Y)$, $(L, M)^{1^0}_\xi \subseteq (N, P)^{1^0}_\xi$, $(L, M)^{2^0}_\xi \subseteq (N, P)^{2^0}_\xi$, $I_\xi(L, M) \subseteq I_\xi(N, P)$ and $I_\xi(I_\xi(L, M)) = I_\xi(L, M)$

Definition 2.6: Let (Y_1, Y_2, ξ) is ξ_T S and (Z, \mathcal{T}) be G_T . Then the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is called ξ -continuous at $z \in Z$ if for any ξ -open set $(L, M) \in (Y_1, Y_2, \xi)$ with $\mathcal{F}(z) \in (L, M)$ then there exists \mathcal{T} -open G in (Z, \mathcal{T}) such that $z \in G$ and $\mathcal{F}(G) \subseteq (L, M)$. The mapping \mathcal{F} is called ξ -continuous if it is ξ -continuous at each $z \in Z$.

Proposition 2.6: Let (Y_1, Y_2, ξ) is ξ_T S and (Z, \mathcal{T}) be G_T . Then the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is called ξ -continuous if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -open in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) .

3. ξ -Pre-Continuous Maps (ξ PCM)

In this section, the concept of ξ -pre-continuous maps, totally ξ -pre-continuous maps and strongly ξ -pre-continuous maps in ξ_T S have been introduced and established the relationships between these maps and some other maps by making the use of some counter examples.

Definition 3.1: Let (Y_1, Y_2, ξ) is ξ_T S. Then $(L, M) \subseteq (Y_1, Y_2, \xi)$ is said to ξ -pre-open set (ξ POS) if $(L, M) \subseteq I_\xi(Cl_\xi(L, M))$. The complement of ξ -pre-open set is ξ -pre-closed set denoted as (ξ PCS).

Definition 3.2: Let (Y_1, Y_2, ξ) is ξ_T S and (Z, \mathcal{T}) be G_T . Then the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is called ξ -pre-continuous map (ξ PCM) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-open in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) .

Definition 3.3: Let (Y_1, Y_2, ξ) is ξ_T S and (Z, \mathcal{T}) be G_T . Then the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is said to be

- i) Totally ξ -continuous map ($T\xi CM$) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -clopen in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) .
- ii) Totally ξ -pre-continuous map ($T\xi PCM$) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-clopen in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) .
- iii) Strongly ξ -continuous map ($S\xi CM$) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -clopen in (Z, \mathcal{T}) for every ξ -set (L, M) in (Y_1, Y_2, ξ) .
- iv) Strongly ξ -pre-continuous map ($S\xi PCM$) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-clopen in (Z, \mathcal{T}) for every ξ -set (L, M) in (Y_1, Y_2, ξ) .

Proposition 3.1:

- i) Every strongly ξ -continuous map in $\xi_T S$ is totally ξ -continuous map
- ii) Every strongly ξ -pre-continuous map in $\xi_T S$ is totally ξ -pre-continuous map
- iii) Every totally ξ -pre-continuous map in $\xi_T S$ is totally ξ -continuous map

Proof: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T and the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is strongly ξ -continuous map. Therefore $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -clopen in (Z, \mathcal{T}) . Thus for every ξ -open set (R, S) , $\mathcal{F}^{-1}(R, S)$ is \mathcal{T} -clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -continuous map. The proof of (ii) and (iii) are quite analogous.

Remark 3.1: The converse of Proposition 3.1 need not be true shown in Example 3.1, Example 3.2 and Example 3.3.

Example 3.1: Let $Z = \{1, 2, 3\}$, $Y_1 = \{m_1, m_2\}$ and $Y_2 = \{l_1, l_2\}$. Then $\mathcal{T} = \{\emptyset, \{1\}, \{3\}, \{1,2\}, \{1,3\}, \{2,3\}, Z\}$ and $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_2\}), (\{m_2\}, \{Y_2\}), (Y_1, Y_2)\}$. Clearly \mathcal{T} is G_T on Z and ξ is ξ_T from Y_1 to Y_2 . Now define $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ by $\mathcal{F}(1) = (m_2, \emptyset) = \mathcal{F}(3)$ and $\mathcal{F}(2) = (\emptyset, l_2)$. Therefore $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_1\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{\emptyset\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -open set in (Y_1, Y_2, ξ) is \mathcal{T} -clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -continuous map but not strongly ξ -continuous map because $\mathcal{F}^{-1}(\{m_2\}, \{\emptyset\}) = \{1,3\}$ and $\mathcal{F}^{-1}(\{\emptyset\}, \{l_2\}) = \{2\}$, where $\{1,3\}$ and $\{2\}$ are not \mathcal{T} -clopen in (Z, \mathcal{T}) .

Example 3.2: In Example 3.1 the \mathcal{T} -pre-clopen in (Z, \mathcal{T}) are $\emptyset, \{1\}, \{3\}, \{1,2\}, \{2,3\}$ and Z . Now $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_2\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{\emptyset\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -open set in (Y_1, Y_2, ξ) is \mathcal{T} -pre-clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -pre-continuous map but not strongly ξ -pre-continuous map because $\mathcal{F}^{-1}(\{m_2\}, \{\emptyset\}) = \{1,3\}$ and $\mathcal{F}^{-1}(\{\emptyset\}, \{l_2\}) = \{2\}$, where $\{2\}$ and $\{1,3\}$ are not \mathcal{T} -pre-clopen in (Z, \mathcal{T}) .

Example 3.3: Let $Z = \{1, 2, 3\}$, $Y_1 = \{m_1, m_2\}$ and $Y_2 = \{l_1, l_2\}$. Then $\mathcal{T} = \{\emptyset, \{1\}, \{1,2\}, \{2,3\}, Z\}$ and $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_2\}), (\{m_2\}, \{Y_2\}), (Y_1, Y_2)\}$. Clearly \mathcal{T} is G_T on Z and ξ is ξ_T from Y_1 to Y_2 . The \mathcal{T} -pre-clopen in (Z, \mathcal{T}) are $\emptyset, \{1\}, \{2\}, \{1,3\}, \{2,3\}$ and Z . Now define $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ by $\mathcal{F}(1) = (m_1, l_2) = \mathcal{F}(3)$ and $\mathcal{F}(2) = (\emptyset, l_2)$. Therefore $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_2\}) = \{1,3\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{\emptyset\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -open set in (Y_1, Y_2, ξ) is \mathcal{T} -pre-clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -pre-continuous map but not ξ -continuous map because $\{1,3\}$ is \mathcal{T} -pre-clopen but not \mathcal{T} -open in (Z, \mathcal{T}) .

Proposition 3.2:

- i) Every ξ -continuous map in $\xi_T S$ is totally ξ -pre-continuous map
- ii) Every totally ξ -continuous map in $\xi_T S$ is totally ξ -pre-continuous map
- iii) Every strongly ξ -continuous map in $\xi_T S$ is strongly ξ -pre-continuous map

Proof: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T and the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -continuous map. Therefore $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -open in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) . Since every \mathcal{T} -open is \mathcal{T} -pre-open in (Z, \mathcal{T}) . Therefore, $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -pre-continuous map. The proof of (ii) and (iii) are quite analogous.

Remark 3.2: The converse of Proposition 3.2 need not be true shown in Example 3.5, Example 3.6 and Example 3.7.

Example 3.5: Let $Z = \{1, 2, 3\}$, $Y_1 = \{m_1, m_2\}$ and $Y_2 = \{l_1, l_2\}$. Then $\mathcal{T} = \{\emptyset, \{1,2\}, \{2,3\}, Z\}$ and $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_2\}), (\{m_2\}, \{Y_2\}), (Y_1, Y_2)\}$. Clearly \mathcal{T} is G_T on Z and ξ is ξ_T from Y_1 to Y_2 . Now define $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ by $\mathcal{F}(1) = (m_1, l_2) = \mathcal{F}(3)$ and $\mathcal{F}(2) = (m_2, l_1)$. Therefore $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_2\}) = \{1,3\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{2\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -open set in (Y_1, Y_2, ξ) is \mathcal{T} -pre-open in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-continuous map but not ξ -continuous map because $\{1,3\}$ and $\{2\}$ are not \mathcal{T} -open in (Z, \mathcal{T}) .

Example 3.6: In Example 3.5, the \mathcal{T} -pre-clopen in (Z, \mathcal{T}) are $\emptyset, \{2\}, \{1,3\}$ and Z . Now $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_2\}) = \{1,3\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{2\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -open set in (Y_1, Y_2, ξ) is \mathcal{T} -pre-clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -pre-continuous map but not totally ξ -continuous map because $\{1,3\}$ and $\{2\}$ are not \mathcal{T} -clopen in (Z, \mathcal{T}) .

Example 3.7: In Example 3.5, the \mathcal{T} -clopen sets in (Z, \mathcal{T}) are $\emptyset, \{2\}, \{1,3\}$ and Z . Now $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_1\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{m_1\}, \{Y_2\}) = \{1,3\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{2\}$, $\mathcal{F}^{-1}(\{\emptyset\}, \{l_1\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{\emptyset\}, \{l_2\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{\emptyset\}, \{Y_2\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{m_1\}, \{\emptyset\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{m_1\}, \{l_2\}) = \{1,3\}$, $\mathcal{F}^{-1}(\{m_1\}, \{Y_2\}) = \{1,3\}$, $\mathcal{F}^{-1}(\{m_2\}, \emptyset) =$

$\{\emptyset\}$, $\mathcal{F}^{-1}(\{m_2\}, \{l_1\}) = \{2\}$, $\mathcal{F}^{-1}(\{m_2\}, \{l_2\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{Y_1\}, \{\emptyset\}) = \{\emptyset\}$, $\mathcal{F}^{-1}(\{Y_1\}, \{l_1\}) = \{2\}$, $\mathcal{F}^{-1}(\{Y_1\}, \{l_2\}) = \{\emptyset\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -set in (Y_1, Y_2, ξ) is \mathcal{T} -pre-clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is strongly ξ -pre-continuous map but not strongly ξ -continuous map because $\{1,3\}$ and $\{2\}$ are not \mathcal{T} -open in (Z, \mathcal{T}) .

Relationships of Various ξ -continuous maps that we discussed in this section:

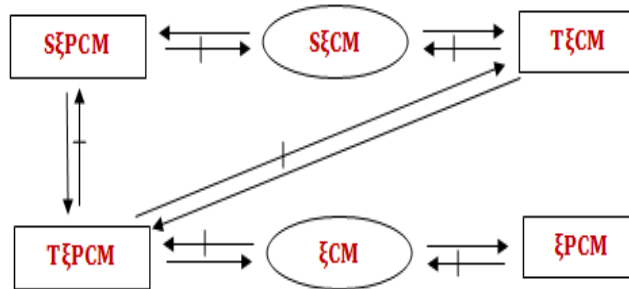


Figure-1

4. ξ -Regular Continuous Maps (ξ RCM)

In this section, we have introduced and studied the concepts of ξ -regular-continuous maps, totally ξ -regular-continuous maps and strongly ξ -regular-continuous maps. Further, the relationships of these maps with some other maps have been established by making the use of some counter examples.

Definition 4.1: Let (Y_1, Y_2, ξ) is $\xi_T S$. Then $(L, M) \subseteq (Y_1, Y_2, \xi)$ is said to ξ -regular-open set (ξROS) if $(L, M) = I_\xi(Cl_\xi(L, M))$. The complement of ξ -regular-open set is ξ -regular-closed set denoted as (ξRCS).

Definition 4.2: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T . Then the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is said to be

- i) ξ -regular-continuous map (ξRCM) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -regular-open in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) .
- ii) Totally ξ -regular-continuous map ($T\xi RCM$) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -regular-clopen in (Z, \mathcal{T}) for every ξ -open set (L, M) in (Y_1, Y_2, ξ) .
- iii) Strongly ξ -regular-continuous map ($S\xi RCM$) if $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -regular-clopen in (Z, \mathcal{T}) for every ξ -set (L, M) in (Y_1, Y_2, ξ) .

Proposition 4.1:

- i) Every strongly ξ -regular-continuous map in $\xi_T S$ is strongly ξ -continuous map
- ii) Every totally ξ -regular-continuous map in $\xi_T S$ is totally ξ -continuous map
- iii) Every ξ -regular-continuous map in $\xi_T S$ is ξ -continuous map

Proof: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T and the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is strongly ξ -regular-continuous map. Therefore $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -regular-clopen in (Z, \mathcal{T}) . Since every \mathcal{T} -regular-clopen is \mathcal{T} -clopen in (Z, \mathcal{T}) . Thus $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is strongly ξ -continuous map. The proof of (ii) and (iii) are quite analogous.

Remark 4.1: The converse of (iii) in Proposition 4.1 is not true seen in Example 4.1.

Example 4.1: Let $Z = \{1, 2, 3, 4\}$, $Y_1 = \{m_1, m_2\}$ and $Y_2 = \{l_1, l_2\}$. Then $\mathcal{T} = \{\emptyset, \{2\}, \{2,3\}, \{3,4\}, \{2,3,4\}, Z\}$ and $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_1\}), (\{m_1\}, \{Y_2\}), (\{m_2\}, \{Y_2\}), (Y_1, Y_2)\}$. Clearly \mathcal{T} is G_T on Z and ξ is ξ_T from Y_1 to Y_2 . Now define $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ by $\mathcal{F}(2) = (m_1, l_1) = \mathcal{F}(3)$ and $\mathcal{F}(1) = \mathcal{F}(4) = (m_1, l_2)$. Therefore $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_1\}) = \{2,3\}$, $\mathcal{F}^{-1}(\{m_1\}, \{Y_2\}) = \{2,3\}$, $\mathcal{F}^{-1}(\{m_2\}, \{Y_2\}) = \{\emptyset\}$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -open set in (Y_1, Y_2, ξ) is \mathcal{T} -open in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -continuous map but not ξ -regular-continuous map because $\{2,3\}$ is not \mathcal{T} -regular-open in (Z, \mathcal{T}) .

Proposition 4.2:

- i) Every strongly ξ -regular-continuous map in $\xi_T S$ is totally ξ -regular-continuous map
- ii) Every totally ξ -regular-continuous map in $\xi_T S$ is ξ -regular-continuous map

Proof: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T and the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is strongly ξ -regular-continuous map. Therefore $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -regular-clopen in (Z, \mathcal{T}) for every ξ -set (L, M) in (Y_1, Y_2, ξ) . Thus for every ξ -open set (R, S) , $\mathcal{F}^{-1}(R, S)$ is \mathcal{T} -regular-clopen in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is totally ξ -regular-continuous map. The proof of (ii) and (iii) are quite analogous.

Relationships of Various ξ -continuous maps that we discussed in this section:

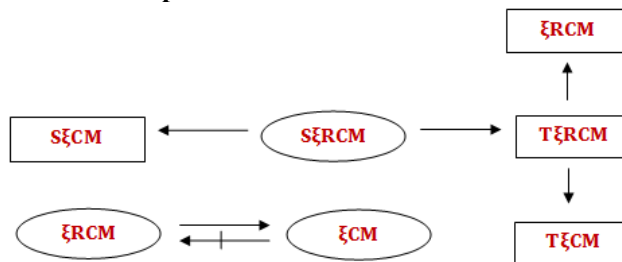


Figure-2

5. ξ -Pre-Generalized Closed Sets and Maps

In this section, we have introduced and studied the concepts of ξ -pre-generalized closed set, ξ -generalized pre-closed set, ξ -pre-generalized maps and ξ -pre-irresolutes. Further, the relationships of these maps with some other maps have been established by making the use of some counter examples.

Definition 5.1: Let (Y_1, Y_2, ξ) is $\xi_T S$. Then $(L, M) \subseteq (Y_1, Y_2, \xi)$ is said to be

- i) ξ -semi-open set (ξSOS) if $(L, M) \subseteq Cl_\xi(I_\xi(L, M))$
- ii) ξ -pre-open set (ξPOS) if $(L, M) \subseteq I_\xi(Cl_\xi(L, M))$.
- iii) ξ - α -open set ($\xi \alpha OS$) if $(L, M) \subseteq I_\xi(Cl_\xi(I_\xi(L, M)))$.

Definition 5.2: Let (Y_1, Y_2, ξ) is $\xi_T S$ and $(L, M) \subseteq (Y_1, Y_2, \xi)$, then $pCl_\xi(L, M) = (L, M) \cup Cl_\xi(I_\xi(L, M))$

Definition 5.3: Let (Y_1, Y_2, ξ) is $\xi_T S$ and $(L, M) \subseteq (Y_1, Y_2, \xi)$, then

- i) (L, M) is ξ -pre-generalized closed set ($\xi PGCS$) if $pCl_\xi(L, M) \subseteq (U, V)$ whenever $(L, M) \subseteq (U, V)$ and (U, V) is ξ -pre-open set in (Y_1, Y_2, ξ)
- ii) (L, M) is ξ -generalized pre-closed set ($\xi GPCS$) if $pCl_\xi(L, M) \subseteq (U, V)$ whenever $(L, M) \subseteq (U, V)$ and (U, V) is ξ -open set in (Y_1, Y_2, ξ)
- iii) (L, M) is ξ^* -closed set ($\xi^* CS$) if $Cl_\xi(L, M) \subseteq (U, V)$ whenever $(L, M) \subseteq (U, V)$ and (U, V) is ξ -open set in (Y_1, Y_2, ξ)

Proposition 5.1: Every ξ -generalized pre-closed set in $\xi_T S$ ξ -pre-generalized closed

Proof: Follows from definition

Remark 5.1: The Converse of Proposition 5.1 is not true in general shown in Example 5.1.

Example 5.1: Let $Y_1 = \{m_1, m_2, m_3\}$ and $Y_2 = \{l_1, l_2, l_3\}$. Then $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_1, l_2\}), (\{m_2, m_3\}, \{l_3\}), (\{l_1, l_3\}, \{Y_2\}), (Y_1, Y_2)\}$. Clearly ξ is ξ_T from Y_1 to Y_2 . Now consider, $(\{m_1, m_2\}, \{l_1, l_2\}) \subseteq (\{m_1, m_2\}, \{Y_2\})$. Therefore $pCl_\xi(\{m_1, m_2\}, \{l_1, l_2\}) = (\{m_1, m_2\}, \{l_1, l_2\}) \subseteq (\{m_1, m_2\}, \{Y_2\})$, where $(\{m_1, m_2\}, \{Y_2\})$ is ξ -pre-open. Therefore $(\{m_1, m_2\}, \{l_1, l_2\})$ is ξ -pre-generalized closed but not ξ -generalized pre-closed because $(\{m_1, m_2\}, \{Y_2\})$ is ξ -pre-open but not ξ -open.

Proposition 5.2: Every \mathcal{T} -pre-closed set in $\xi_T S$ is \mathcal{T} -pre-generalized closed

Proof: Obvious

Remark 5.2: The converse of Proposition 5.2 is not true in general shown in Example 5.2.

Example 5.2: Let $Z = \{1, 2, 3, 4\}$. Then $\mathcal{T} = \{\emptyset, \{1\}, \{1, 2\}, \{1, 2, 3\}, \{3, 4\}, \{1, 3, 4\}, Z\}$ is G_T on Z . Consider the set $\{1, 3\} \subseteq \{1, 2, 3\}$. Therefore $p - \mathcal{T}_g(\{1, 3\}) = \{1, 2, 3\} \subseteq \{1, 2, 3\}$, where $\{1, 2, 3\}$ is \mathcal{T} -pre-open. Therefore the set $\{1, 3\}$ is \mathcal{T} -pre-generalized closed but not \mathcal{T} -pre-closed.

Remark 5.3: In general ξ^* -closed set and ξ -pre-generalized closed set in $\xi_T S$ are independent shown in Example 5.3 and Example 5.4.

Example 5.3: Let $Y_1 = \{m_1, m_2, m_3\}$ and $Y_2 = \{l_1, l_2\}$. Then $\xi = \{(\emptyset, \emptyset), (\emptyset, \{l_2\}), (\{Y_1\}, \{l_1\}), (\{m_1, m_2\}, \{Y_2\}), (Y_1, Y_2)\}$ is ξ_T from Y_1 to Y_2 . Clearly the sets (\emptyset, \emptyset) , $(\{Y_1\}, \{l_1\})$, $(\emptyset, \{l_2\})$ and (Y_1, Y_2) are ξ -closed sets in (Y_1, Y_2, ξ) . Let $(\{m_2\}, \{Y_2\}) \in \wp(Y_1) \times \wp(Y_2)$. Then $Cl_\xi(\{m_2\}, \{Y_2\}) = (Y_1, Y_2) \subseteq (Y_1, Y_2)$ where $(\{m_2\}, \{Y_2\}) \subseteq (Y_1, Y_2)$ and (Y_1, Y_2) is ξ -open. Therefore the set $(\{m_2\}, \{Y_2\})$ is ξ^* -closed set but not ξ -pre-generalized closed set because $(\{m_2\}, \{Y_2\}) \subseteq (\{m_1, m_2\}, \{Y_2\})$ and $pCl_\xi(\{m_2\}, \{Y_2\}) = (Y_1, Y_2) \not\subseteq (\{m_1, m_2\}, \{Y_2\})$, where $(\{m_1, m_2\}, \{Y_2\})$ is ξ -pre-open.

Example 5.4: Let $Y_1 = \{m_1, m_2, m_3\}$ and $Y_2 = \{l_1, l_2, l_3\}$. Then $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_1, l_2\}), (\{m_2, m_3\}, \{l_3\}), (\{m_1, m_2\}, \{Y_2\}), (Y_1, Y_2)\}$ is ξ_T from Y_1 to Y_2 . Consider the set $(\{m_1, m_3\}, \{l_1, l_2\}) \subseteq (\{m_1, m_3\}, \{Y_2\})$. Therefore $pCl_\xi(\{m_1, m_3\}, \{l_1, l_2\}) = (\{m_1, m_3\}, \{l_1, l_2\}) \subseteq (\{m_1, m_3\}, \{Y_2\})$, where $(\{m_1, m_3\}, \{Y_2\})$ is ξ -pre-open. Therefore $(\{m_1, m_3\}, \{l_1, l_2\})$ is ξ -pre-generalized closed set open but not ξ^* -closed set because $Cl_\xi(\{m_1, m_3\}, \{l_1, l_2\}) = (Y_1, Y_2) \not\subseteq (\{m_1, m_3\}, \{Y_2\})$ where $(\{m_1, m_3\}, \{l_1, l_2\}) \subseteq (\{m_1, m_3\}, \{Y_2\})$ and $(\{m_1, m_3\}, \{Y_2\})$ is ξ -open.

Definition 5.4: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T . Then the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is said to be
 i) ξ -pre-generalized continuous map ($\xi PGCM$) $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) for every ξ -closed set (L, M) in (Y_1, Y_2, ξ) .
 ii) ξ -pre-irresolute (ξPI) $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-closed in (Z, \mathcal{T}) for every ξ -pre-closed set (L, M) in (Y_1, Y_2, ξ) .
 iii) ξ -pre-generalized irresolute (ξPGI) $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) for every ξ -pre-generalized closed set (L, M) in (Y_1, Y_2, ξ) .

Proposition 5.3: Every ξ -pre-continuous map in $\xi_T S$ is ξ -pre-generalized continuous

Proof: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T and the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-continuous map. Therefore $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-closed in (Z, \mathcal{T}) for every ξ -closed set (L, M) in (Y_1, Y_2, ξ) . Since every \mathcal{T} -pre-closed is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) . Thus $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-generalized continuous map.

Remark 5.4: The Converse of Proposition 5.3 is not true in general shown in Example 5.5.

Example 5.5: Let $Z = \{1, 2, 3, 4\}$, $Y_1 = \{m_1, m_2\}$ and $Y_2 = \{l_1, l_2\}$. Then $\mathcal{T} = \{\emptyset, \{1\}, \{1, 2\}, \{1, 2, 3\}, \{3, 4\}, \{1, 3, 4\}, Z\}$ and $\xi = \{(\emptyset, \emptyset), (\{m_1\}, \{l_1\}), (\{m_2\}, \{l_2\}), (\{m_2\}, \{Y_2\}), (Y_1, Y_2)\}$. Clearly \mathcal{T} is G_T on Z and ξ is ξ_T from Y_1 to Y_2 . Now define $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ by $\mathcal{F}(1) = (m_1, l_1) = \mathcal{F}(3)$ and $\mathcal{F}(2) = (m_2, \emptyset)$. Therefore $\mathcal{F}^{-1}(\emptyset, \emptyset) = \emptyset$, $\mathcal{F}^{-1}(\{m_1\}, \{l_1\}) = \{1, 3\}$, $\mathcal{F}^{-1}(\{m_2\}, \{l_2\}) = \{2\}$, $\mathcal{F}^{-1}(\{m_1\}, \emptyset) = \emptyset$ and $\mathcal{F}^{-1}(Y_1, Y_2) = Z$. This shows that the inverse image of every ξ -closed set in (Y_1, Y_2, ξ) is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-generalized continuous map but not ξ -pre-continuous map because $\{1, 3\}$ is not \mathcal{T} -pre-closed in (Z, \mathcal{T}) .

Proposition 5.4: Every ξ -pre-continuous map in $\xi_T S$ is ξ -pre-generalized irresolute.

Proof: Let (Y_1, Y_2, ξ) is $\xi_T S$ and (Z, \mathcal{T}) be G_T and the map $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-continuous map. Therefore $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-closed in (Z, \mathcal{T}) for every ξ -closed set (L, M) in (Y_1, Y_2, ξ) . Since every \mathcal{T} -pre-closed is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) and like wise every ξ -pre-closed set is ξ -pre-generalized closed set in (Y_1, Y_2, ξ) . Thus $\mathcal{F}^{-1}(L, M)$ is \mathcal{T} -pre-generalized closed in (Z, \mathcal{T}) for every ξ -pre-generalized closed set in (Y_1, Y_2, ξ) . Hence $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-generalized irresolute.

Remark 5.5: The Converse of Proposition 5.4 is not true in general which can be easily seen from Example 5.5.

Proposition 5.5: Every ξ -pre-irresolute in $\xi_T S$ is ξ -pre-generalized irresolute.

Proof: Follows from definition, while the converse need not be true in general shown in Example 5.6.

Example 5.6: In Example 5.5, $\mathcal{F}: (Z, \mathcal{T}) \rightarrow Y_1 \times Y_2$ is ξ -pre-generalized irresolute but not ξ -pre-irresolute.

Relationships of Various ξ -continuous maps that we discussed in this section:

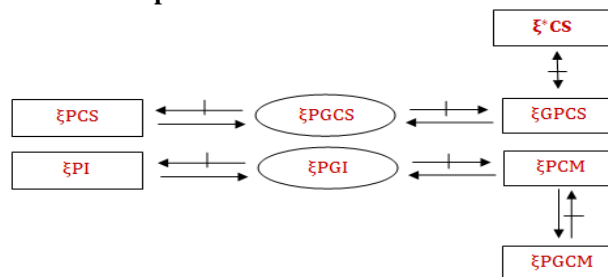


Figure-3

6. Conclusion

In this paper, a very useful concept of ξ -pre-continuous maps, totally ξ -pre-continuous maps and strongly ξ -pre-continuous maps in ξ -topological spaces have been introduced and established the relationships between these maps and some other maps. Further the concepts of ξ -regular-continuous maps, totally ξ -regular-continuous maps and strongly ξ -regular-continuous maps have been introduced along with some concepts of ξ -pre-generalized closed set, ξ -generalized

pre-closed set, ξ -pre-generalized maps and ξ -pre-irresolutes with the relationships of these particular types of sets and maps in ξ -topological spaces. All the relationships have been verified by making the use of some examples.

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